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PHYSICAL APPLICATIONS OF GEOMETRIC ALGEBRA

LECTURE 14

SUMMARY

The key to deriving the field equations in a gauge theory is the covariant **field strength tensor**. In this lecture we study the properties of these for the two gravitational **gauge fields**.

- Commutators of covariant derivatives and the **field strength**.
- The gravitational field strength and **non-linearity**.
- The **Riemann tensor**, and some simple examples.
- The **Planck scale** and the magnitude of the field strength of the displacement field.
- Further properties of the Riemann tensor.
- The second field equation.

THE FIELD STRENGTH

Form **commutator** of covariant derivatives. First take electromagnetism, $\psi \mapsto \psi R$. With a and b constant vectors, get

$$[D_a, D_b]\psi = \frac{1}{2}\psi[a \cdot \nabla \Omega(b) - b \cdot \nabla \Omega(a) - \Omega(a) \times \Omega(b)]$$

All **derivatives** of ψ have **canceled**.

Restricting to $\Omega(a) = -2a \cdot A I\sigma_3$, get term in

$$\begin{aligned} b \cdot \nabla(a \cdot A I\sigma_3) - a \cdot \nabla(b \cdot A I\sigma_3) - 2a \cdot A b \cdot A I\sigma_3 \times I\sigma_3 \\ = (a \wedge b) \cdot (\nabla \wedge A) I\sigma_3 = (a \wedge b) \cdot F I\sigma_3 \end{aligned}$$

Maps bivector $a \wedge b$ **linearly** onto a pure phase term. In electromagnetism lose mapping and extract $F = \nabla \wedge A$. This is physical field. **Vanishes** if A is pure gauge.

ROTATION GAUGE

For rotations, rotors multiply ψ from **left**, so

$$[D_a, D_b]\psi = \frac{1}{2}R(a \wedge b)\psi$$

where

$$R(a \wedge b) = a \cdot \nabla \Omega(b) - b \cdot \nabla \Omega(a) + \Omega(a) \times \Omega(b)$$

Right-hand side is **antisymmetric** on a, b , so a **linear function**

of the bivector $a \wedge b$. Extend to general bivectors

$$R(a \wedge b + c \wedge d) = R(a \wedge b) + R(c \wedge d).$$

Can write the field strength as,

$$R(B) = R(B; x)$$

- A **position dependent, linear function** of the bivector B . Returns a general bivector, so $6 \times 6 = 36$ Degrees of freedom.
- Term in $\Omega(a) \times \Omega(b)$ is **non-linear**. Cannot superpose two solutions to get a third. **Much** more difficult than electromagnetism.

Transformation properties easy to establish

$$\begin{aligned} [D'_a, D'_b] \psi' &= \frac{1}{2} R'(a \wedge b) R \psi \\ &= R [D_a, D_b] \psi = \frac{1}{2} R R (a \wedge b) \psi \end{aligned}$$

so read off that

$$R'(a \wedge b) = R R (a \wedge b) \tilde{R}.$$

Field strength now **transforms** under gauge transformations.

If $\Omega(a)$ pure gauge, then can find gauge where $D_a = a \cdot \nabla$.

$R(a \wedge b)$ vanishes in this gauge, so vanishes in **all** gauges.

DISPLACEMENT GAUGE

$\bar{h}(a)$ couples to derivatives differently. Form commutator, now get

$$[a \cdot \bar{h}(\nabla), b \cdot \bar{h}(\nabla)]\psi = (b \wedge a) \cdot [\bar{h}(\nabla) \wedge \bar{h}(\nabla)]\psi.$$

Now do get a differential operator. driven by $\bar{h}(\nabla) \wedge \bar{h}(\nabla)$ term. Acting on scalar ϕ

$$\begin{aligned} \bar{h}(\nabla) \wedge \bar{h}(\nabla \phi) &= \bar{h}(\dot{\nabla}) \wedge \dot{\bar{h}}(\nabla \phi) + \bar{h}(\nabla \wedge \nabla \phi) \\ &= \bar{h}(\dot{\nabla}) \wedge \dot{\bar{h}}(\nabla \phi) \end{aligned}$$

where over-dot again denotes **scope** of derivative. Now $\bar{h}(\nabla \phi)$ is covariant. So generalise to

$$S(a) = \bar{h}(\dot{\nabla}) \wedge \dot{\bar{h}}\bar{h}^{-1}(a) = -\bar{h}[\nabla \wedge \bar{h}^{-1}(a)],$$

where a is a constant vector, and have used

$$\nabla \wedge [\bar{h}\bar{h}^{-1}(a)] = \dot{\nabla} \wedge \dot{\bar{h}}\bar{h}^{-1}(a) + \dot{\nabla} \wedge \bar{h}\dot{\bar{h}}^{-1}(a) = \nabla \wedge a = 0.$$

$S(a)$ is covariant under displacements. What about pure gauge? In this case

$$\bar{h}(a) = \bar{f}^{-1}(a),$$

so that $\bar{h}(\nabla) = \bar{f}^{-1}(\nabla) = \nabla_{x'}$ is **vector derivative** in some

other gauge. For this case

$$S(a) = -\bar{f}^{-1}[\nabla \wedge \bar{f}(a)].$$

But $f(a)$ is the derivative of a displacement,

$$f(a) = a \cdot \nabla f(x),$$

so

$$\bar{f}(a) = \partial_b \langle f(b)a \rangle = \partial_b \langle b \cdot \nabla f(x)a \rangle = \nabla(a \cdot f(x)).$$

Henced $\nabla \wedge \bar{f}(a) = \nabla \wedge \nabla(a \cdot f(x)) = 0$. $S(a)$ has the desired properties.

COVARIANT FIELD STRENGTHS

Need **covariant** forms of field strength. Start with **rotation gauge**. $\Omega(a)$ removes terms in $a \cdot \nabla R \tilde{R}$. Under displacements must have

$$\Omega(a; x) \mapsto \Omega'(a; x) = \Omega[f(a); x']$$

Field strength has term in $\Omega(a) \times \Omega(b)$. Must transform to

$$R(a \wedge b) \mapsto R'(a \wedge b) = R[f(a) \wedge f(b)] = R[f(a \wedge b); x']$$

Picks up a term in $f(B)$. Remove this with suitable version of $\bar{h}(a)$. Has

$$\bar{h}(a) \mapsto \bar{h}'(a) = \bar{h}\bar{f}^{-1}(a)$$

so adjoint transforms as

$$h(a) \mapsto h'(a) = f^{-1}h(a).$$

Insert this into $\mathcal{R}(B)$. Define covariant field strength

$$\mathcal{R}(B) = R[h(B)]$$

Factor of $h(B)$ alters rotation gauge properties.

$$\bar{h}(a) \mapsto \bar{h}'(a) = R\bar{h}(a)\tilde{R}.$$

so adjoint goes as

$$h(a) \mapsto h'(a) = \partial_b \langle a R \bar{h}(b) \tilde{R} \rangle = h(\tilde{R} a R).$$

Summarised transformation properties of $\mathcal{R}(B)$ by:

$$\text{Displacements:} \quad \mathcal{R}'(B, x) = \mathcal{R}(B, x')$$

$$\text{Rotations:} \quad \mathcal{R}'(B) = R\mathcal{R}(\tilde{R}BR)\tilde{R}.$$

Just what we want for a **covariant tensor**. Call $\mathcal{R}(B)$ the **Riemann tensor**. Understand rotation transformation from

$$\mathcal{R}(B) = \alpha B$$

This is 'dilate all fields by factor α '. Transformed field is

$$\mathcal{R}'(B) = R\mathcal{R}(\tilde{R}BR)\tilde{R} = R(\alpha\tilde{R}BR)\tilde{R} = \alpha B$$

Same **physical information**.

EXAMPLES

I. The Schwarzschild Solution

Spherically symmetric source, mass M at rest in γ_0 frame, has

$$\mathcal{R}(B) = -\frac{M}{2r^3}(B + 3\sigma_r B \sigma_r)$$

where $r = |x \wedge \gamma_0|$, $\sigma_r = x \wedge \gamma_0 / r$. $M/2r^3$ controls the **tidal force**. In empty space these are measurable.

II. The Kerr Solution

Outside a **rotating** black hole get

$$\mathcal{R}(B) = -\frac{M}{2(r + IL \cos\theta)^3}(B + 3\sigma_r B \sigma_r).$$

Get Schwarzschild by $r \mapsto r + IL \cos\theta$. Explains **complex structure** in Kerr solution!

III. Cosmic Strings

Infinite, pressure-free string along γ_3 , density ρ has

$$\mathcal{R}(B) = 8\pi\rho \langle B I \sigma_3 \rangle I \sigma_3$$

Get tidal forces in $I\sigma_3$ plane only. Magnitude determined by density.

IV. Cosmology

Isotropic, homogeneous cosmology has

$$\mathcal{R}(B) = 4\pi(\rho + P)B \cdot e_t e_t - \frac{1}{3}(8\pi\rho + \Lambda)B.$$

P and ρ are pressure and density, Λ is the **cosmological constant**, and e_t is 'rest-frame' of the universe (defined by the **cosmic microwave background radiation**). No other direction present.

DISPLACEMENT GAUGE AGAIN

Key quantity is

$$\mathcal{S}(a) = -\bar{h}[\nabla \wedge \bar{h}^{-1}(a)] = \bar{h}(\dot{\nabla}) \wedge \dot{\bar{h}}\bar{h}^{-1}(a).$$

But $\bar{h}(a)$ picks up additional rotors under rotation gauge.

Replace the directional derivatives by covariant derivatives:

$$\mathcal{S}(a) = \bar{h}(\partial_b) \wedge \left(b \cdot \dot{\nabla} \dot{\bar{h}}\bar{h}^{-1}(a) + \Omega(b) \cdot a \right).$$

Guarantees required transformation laws

$$\text{Displacements:} \quad \mathcal{S}'(a, x) = \mathcal{S}(a, x')$$

$$\text{Rotations:} \quad \mathcal{S}'(a) = R\mathcal{S}(\tilde{R}aR)\tilde{R}.$$